

Cross-domain Speech Recognition with Unsupervised Character-level Distribution Matching

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Introduction

- Background

- Distribution mismatch leads to deterioration in automatic speech recognition (ASR)
- Example: cross-device, cross-environment ASR
- It is expensive and time-consuming to collect labeled speech data from massive domains (distributions)

- Unsupervised Domain Adaptation (UDA)

- Existing methods

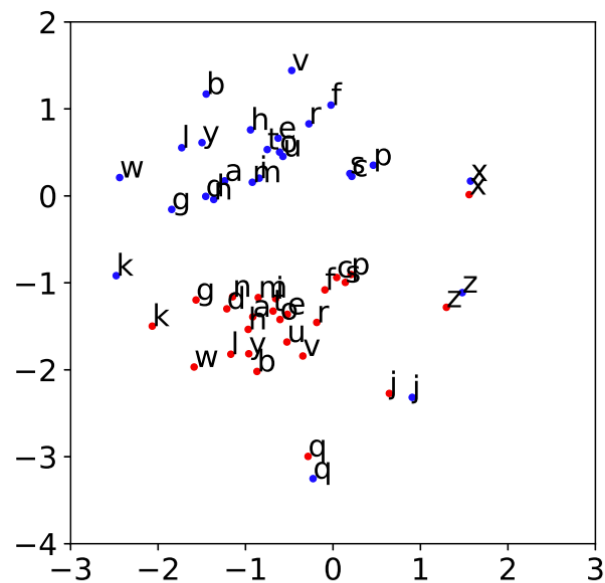
- Data augmentation + representation matching
- Self-training with pseudo-label filtering approach based on the model's uncertainty using dropout
- Domain-adversarial training

- Limitation

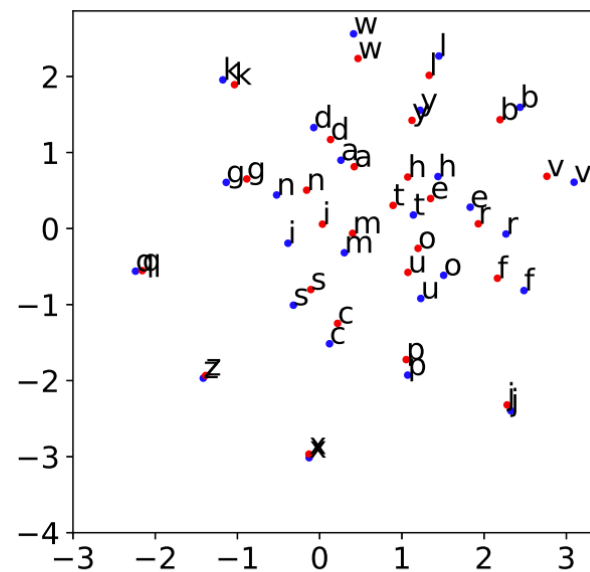
- Ignoring the fine-grained knowledge (characters, phoneme, and word) may result in unsatisfying results

CMatch

- Character-level distribution matching
 - $P(y|X)$
 - Why not word or utterance matching?
 - Word or utterance are highly sparse
 - No segmentation ground-truth in end-to-end ASR models



(a) Before CMatch



(b) After CMatch

Preliminary

- CTC-Attention Transformer ASR Model

- Input: 83-dimensional filter banks with pitch features (10 ms frame shift, 25 ms frame length)

- Network Structure:

- 12 encoder Layers (self-attention, feed-forward)

- CTC module: output CTC predictions

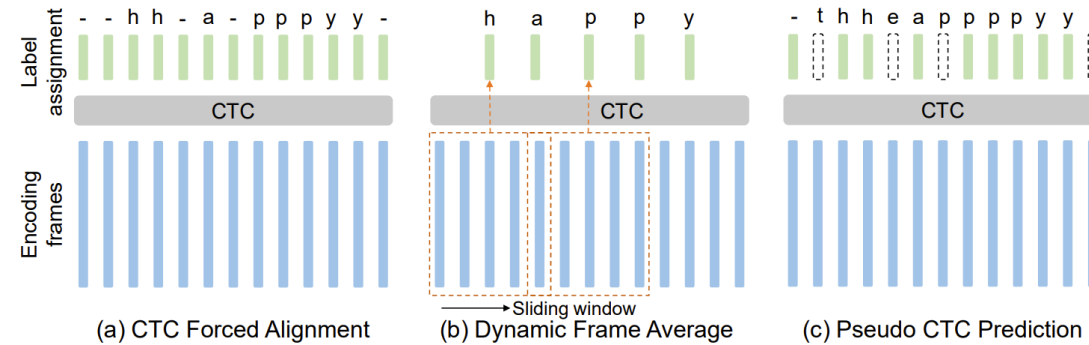
- 6 decoder layers (self-attention, cross-attention, feed-forward)

- Training: $\mathcal{L}_{ASR} = (1 - \lambda)\mathcal{L}_{ATT} + \lambda\mathcal{L}_{CTC}$

- Decoding: $\hat{Y} = \arg \max_{Y \in \mathcal{Y}} (1 - \lambda) \log P_{ATT}(Y|X) + \lambda \log P_{CTC}(Y|X)$

CMatch: Character-level Distribution Matching

- Frame-level Label Assignment



- CTC forced alignment

- Take the labels from the most probable path selected by CTC forward-backward algorithm as the frame-level assignment
- Effective but computationally expensive

- Dynamic Frame Average

- Assign frames for each character by sliding window averaging
- Work in a strict condition that the character output is a uniform distribution

- Pseudo CTC Prediction

- CTC model naturally predicts the label assignment frame by frame which can be directly utilized
- Filter out the CTC predictions with a threshold 0.9 based on their softmax scores to improve the accuracy

$$\hat{Y}_n = \arg \max_{Y_n} P_{\text{CTC}}(Y_n | X_n), \quad 1 \leq n \leq N$$

Distribution Matching

- Maximum Mean Discrepancy (MMD)

- MMD is a non-parametric criterion to empirically evaluate the divergence between two distribution

- Formulation:

$$\text{MMD}(\mathcal{H}_k, P, Q) = \sup_{\|\phi\|_{\mathcal{H}_k} \leq 1} \mathbb{E}_{X_S \sim P} \phi(X_S) - \mathbb{E}_{X_T \sim Q} \phi(X_T)$$

- Biased empirical estimate:

$$\text{MMD}(\mathcal{H}_k, X_S, X_T) = \sup_{\|\phi\|_{\mathcal{H}_k} \leq 1} \left(\frac{1}{|X_S|} \sum_{x_s \in X_S} \phi(x_s) - \frac{1}{|X_T|} \sum_{x_t \in X_T} \phi(x_t) \right)$$

- Character-level Distribution Matching Loss

$$\mathcal{L}_{\text{cmatch}} = \frac{1}{|\mathcal{C}|} \sum_{c \in \mathcal{C}} \text{MMD}(\mathcal{H}_k, X_S^c, X_T^c)$$

Learning Algorithm

- Overall Loss

$$\mathcal{L} = \frac{1}{2} (\mathcal{L}_{\text{ASR}}^{\text{src}} + \mathcal{L}_{\text{ASR}}^{\text{tgt}}) + \gamma \mathcal{L}_{\text{cmatch}}$$

- Learning algorithm

Algorithm 1 Learning algorithm of CMatch

Input: Source domain (X_S, Y_S) , target domain X_T .

- 1: Train network M_S on source domain (X_S, Y_S) .
 - 2: Obtain pseudo label \hat{Y}_T with M_S .
 - 3: **while** not done **do**
 - 4: Obtain the frame-level labels.
 - 5: Joint optimization using the overall loss
 - 6: **end while**
 - 7: **return** Adapted model $M_{S \rightarrow T}$ and target transcripts.
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Experimental Setup

- Dataset: Libri-Adapt

- Cross-device: Matrix Voice (M), PlayStation Eye (P), and ReSpeaker (R)
- Cross-environment: clean, rain, wind, laughter
- Number of utterances (hours)
 - Training: 25685 (93.77)
 - Validation: 2854 (10.71)
 - Testing: 2600 (5.60)

- Baselines

- Source-only
- MMD-ASR
- Domain Adversarial Training (ADV)

Cross-domain Adaptation Results

- In-domain

Domain	WER
Matrix Voice (M)	24.25
PlayStation Eye (P)	20.07
ReSpeaker (R)	23.78
Average	22.70

- Device Adaptation

Task	Source-only	MMD	ADV	CMatch
M → P	23.87	20.87	21.11	20.38
M → R	25.21	22.21	22.27	21.77
P → M	31.15	27.22	28.29	26.17
P → R	23.99	21.90	21.74	20.43
R → M	32.45	28.27	29.95	27.77
R → P	23.48	21.09	21.23	20.58
Average	26.69	23.59	24.10	22.85

14.39% improvement

- Noise Adaptation

Target	Source-only	MMD	ADV	CMatch
Rain	38.21	33.61	34.65	32.90
Wind	29.70	26.06	26.73	23.12
Laughter	33.36	29.85	30.41	28.55
Average	33.76	29.84	30.60	28.19

16.50% improvement

Additional Experiments

- Ablation Study
 - Both self-training and distribution matching are effective
- Analyzing the Label Assignment
 - Our pseudo method can be efficient and effective
- Adapting with Decoder
 - Decoder adaptation is not necessary

Variant	Device	Noise
Source-only	26.69	33.76
w/ self-training	22.99	28.31
w/ distribution matching	23.87	30.43
All	22.85	28.19

Task	PseudoCTCPred	FrameAverage	CTCAlign
M → P	20.38	20.21	20.23
M → R	21.77	21.80	21.75
P → M	26.17	26.02	25.84
P → R	20.43	20.36	20.44
R → M	27.77	27.94	27.73
R → P	20.58	20.55	20.52
Average	22.85	22.81	22.75

Target	w/o decoder	first	last	all
Rain	32.90	32.92	32.85	33.12
Wind	23.12	23.18	23.18	23.28
Laughter	28.55	28.66	28.56	28.63
Average	28.19	28.25	28.20	28.34

Summary

- We propose CMatch to match the character-level distributions from the source and target domain
- We empirically analyze the contribution of Transformer encoders and decoders as well as different label assignment strategies
- CMatch outperforms existing approaches on both device and noise adaptation tasks by leveraging the fine-grained information

Q & A